

# NatSTV: Towards Verification of Natural Strategic Ability

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# Motivation

Analyzing voting protocols



# Voting / e-voting protocol

Cryptography

Procedures

Attacker/intruder

Security

Human factor

# Human factor



Makes a mistake



Ignores instructions



Skips the procedure, because it's too complex, time-consuming, hard to understand...



Can affect the security of the system

# Analyzing the voting system

01

Create the  
(simplified)  
model of the  
system

02

Focus on the  
voter's behavior  
and her point of  
view

03

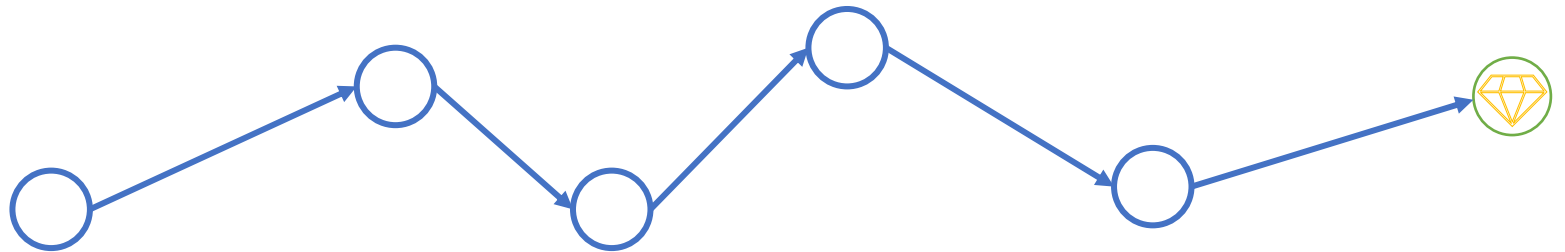
Describe  
requirements  
using ATL/NatATL  
formulae

04

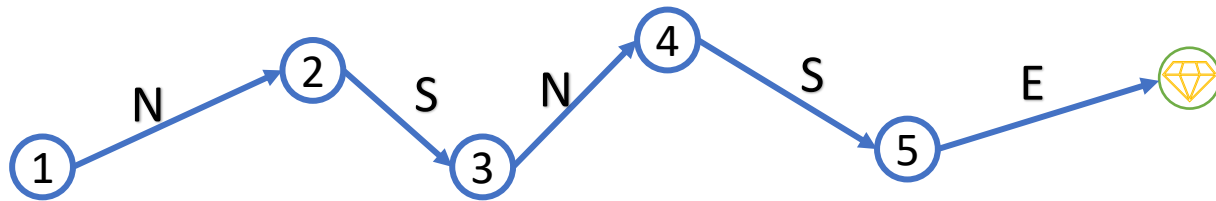
Create natural  
strategies for the  
voter (and other  
agents)

# Strategy

- A plan
- A path in the model



## Strategy description



1: N

2: S

3: N

4: S

5: E

# Classic strategy



Complex



Long



Easy for the computer



Hard for the human





# Natural Strategy

Conditional  
plan

Decisions are  
based on some  
observations

Based on the  
human  
behavior

# Natural Strategy for the Voter

1. Out of the polling station -> go to the polling station



2. Empty ballot -> fill your ballot



3. Filled ballot -> cast your vote



# Strategy in reality



Understand the rules of the voting procedure



Check if your vote is correct



Verify that your vote has been counted correctly



Sign-in to the e-voting system



And much more ...



# Background

Logics and strategies

# ATL: What Agents Can Achieve

- ATL: Alternating-time Temporal Logic [Alur et al. 1997-2002]
- Temporal logic meets game theory
- Main idea: cooperation modalities
- $\langle\langle A \rangle\rangle\phi$ : **coalition  $A$  has a collective strategy to enforce  $\phi$**
- $\phi$  can include temporal operators: X (next), F (sometime in the future), G (always in the future), U (strong until)

## Example Formula

- $\langle\langle \textit{Client} \rangle\rangle F \textit{ ticket}$
- Client can eventually buy a ticket

# Strategy

A *strategy* of agent  $a \in \mathbb{A}gt$  is a conditional plan that specifies what  $a$  is going to do in every possible situation.

Formally, a perfect information memoryless strategy for  $a$  can be represented by a function  $s_a: St \rightarrow Act$  satisfying  $s_a(q) \in d_a(q)$  for each  $q \in St$ .

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An *imperfect information memoryless strategy* additionally satisfies  $s_a(q) = s_a(q')$  whenever  $q \sim_a q'$



# Natural ATL

- Strategies in a form of a set of simple conditions: guarded actions
- Strategy complexity represented as the total lengths of guards in the strategy
- $\langle\langle A \rangle\rangle^{\leq k} \phi$ : coalition  $A$  has a collective strategy of size less or equal than  $k$  to enforce  $\phi$
- $\langle\langle Client \rangle\rangle^{\leq 10} F \text{ ticket}$
- Client can buy a ticket by a strategy of complexity at most 10

# Example Strategy

1.  $\neg ticket \wedge \neg selected \wedge \neg paid \wedge \neg error \rightarrow \textit{select}$
2.  $selected \rightarrow \textit{pay}$
3.  $\top \rightarrow \textit{idle}$

# Example Strategy Complexity

1.  $\neg ticket \wedge \neg selected \wedge \neg paid \wedge \neg error \rightarrow \textit{select}$

**cost = 11**

2.  $selected \rightarrow \textit{pay}$

**cost = 1**

3.  $\top \rightarrow \textit{idle}$

**cost = 1**

Complexity: **11 + 1 + 1 = 13**



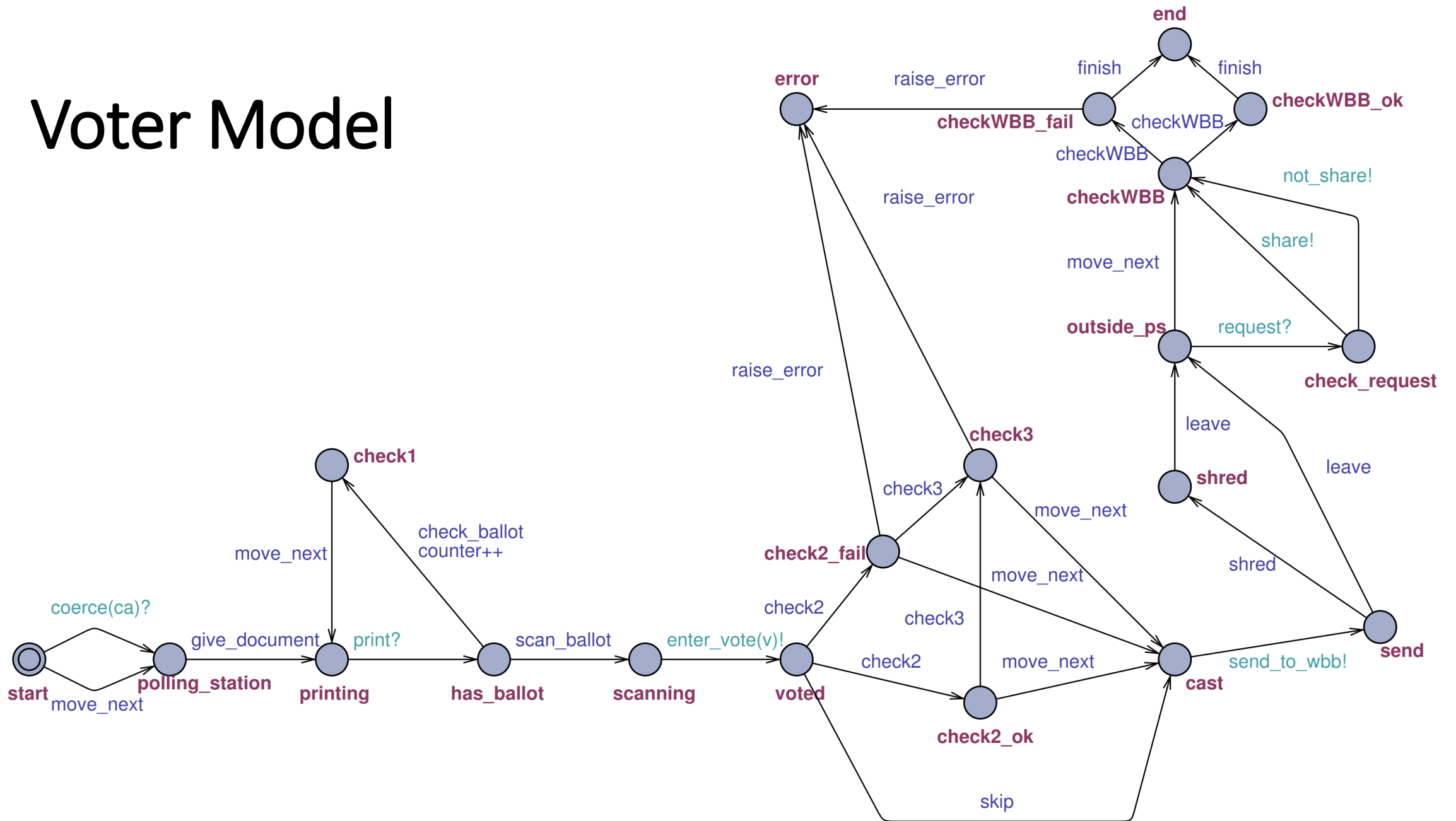
# Case Study

vVote voting system

# Example case study: vVote

- Implementation of *Prêt à Voter* protocol
- Used for remote voting and voting of handicapped persons in the Australian state of Victoria elections in November 2014
- **Main idea:** encoding the vote using a randomized candidate list

# Voter Model



$$\varphi_1 = \langle\langle voter \rangle\rangle \leq^k F(\text{checkWBB\_ok} \vee \text{checkWBB\_fail})$$

- (1)  $\text{start} \vee \text{check2\_ok} \vee \text{check2\_fail} \vee \text{outside\_ps} \rightsquigarrow \text{move\_next}$
- (2)  $\text{polling\_station} \rightsquigarrow \text{give\_document}$
- (3)  $\text{has\_ballot} \rightsquigarrow \text{scan\_ballot}$
- (4)  $\text{scanning} \rightsquigarrow \text{enter\_vote}(v)$
- (5)  $\text{voted} \rightsquigarrow \text{check2}$
- (6)  $\text{cast} \rightsquigarrow \text{send\_to\_wbb}$
- (7)  $\text{send} \rightsquigarrow \text{shred}$
- (8)  $\text{shred} \rightsquigarrow \text{leave}$
- (9)  $\text{check\_request} \rightsquigarrow \text{not\_share}$
- (10)  $\text{checkWBB} \rightsquigarrow \text{checkWBB}$
- (11)  $\top \rightsquigarrow \star$

# Complexity

- 11 guarded commands
- (1)  $\text{start} \vee \text{check2\_ok} \vee \text{check2\_fail} \vee \text{outside\_ps}$ : cost 7
- Other guarded commands cost 1
- Total complexity:  $1 * 10 + 7 * 1 = \mathbf{17}$
- The formula  $\varphi_1$  is true with any  $k$  of 17 and more



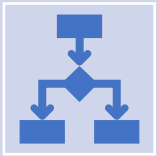
# Example construction of the strategy for $\varphi_1$

- (1)  $\text{has\_ballot} \rightsquigarrow \text{scan\_ballot}$
- (2)  $\neg \text{has\_ballot} \wedge \text{scanning} \rightsquigarrow \text{enter\_vote}$
- (3)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \text{voted} \rightsquigarrow \text{check2}$
- (4)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge (\text{check2\_ok} \vee \text{check2\_fail}) \rightsquigarrow \text{move\_next}$
- (5)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \text{cast} \rightsquigarrow \text{send\_to\_wbb}$
- (6)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \neg \text{cast} \wedge \text{send} \rightsquigarrow \text{shred}$
- (7)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \neg \text{cast} \wedge \neg \text{send} \wedge \text{shred} \rightsquigarrow \text{leave}$
- (8)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \neg \text{cast} \wedge \neg \text{send} \wedge \neg \text{shred} \wedge \text{check\_request} \rightsquigarrow \text{not\_share}$
- (9)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \neg \text{cast} \wedge \neg \text{send} \wedge \neg \text{shred} \wedge \neg \text{check\_request} \wedge \text{checkWBB} \rightsquigarrow \text{checkWBB}$
- (10)  $\neg \text{has\_ballot} \wedge \neg \text{scanning} \wedge \neg \text{voted} \wedge \neg(\text{check2\_ok} \vee \text{check2\_fail}) \wedge \neg \text{cast} \wedge \neg \text{send} \wedge \neg \text{shred} \wedge \neg \text{check\_request} \wedge \neg \text{checkWBB} \rightsquigarrow \star$



# Challenges

# Problems to solve



Finding (one of possibly many) natural strategy for the given formulae (if the strategy exists)



**Minimizing** the representation/complexity of the found strategy

# Problems to solve



Finding (one of possibly many) natural strategy for the given formulae (if the strategy exists)



**Minimazing** the representation/complexity of the found strategy

# Strategy representation example 1

q1	q2	q3	q4	act
1	0	0	0	A
0	1	1	0	B
0	1	0	0	C

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**After reduction:**

q1	q3	act
1		A
	1	B
		C

# Strategy representation example 1

q1	q2	q3	q4	act
1	0	0	0	A
0	1	1	0	B
0	1	0	0	C

**After reduction:**

q1	q3	act
1		A
	1	B
		C

**Natural strategy:**

1.  $q1 \rightarrow A$
2.  $q3 \rightarrow B$
3.  $\top \rightarrow C$

# Strategy representation example 2

q1	q2	q3	q4	act
1	0	0	0	A
0	1	0	1	A
1	1	0	0	B
0	1	1	0	B



# Strategy representation example 2

q1	q2	q3	q4	act
1	0	0	0	A
0	1	0	1	A
1	1	0	0	B
0	1	1	0	B

**After reduction:**

q1	q2	q4	act
1	1		B
1			A
		1	A
			B

# Strategy representation example 2

q1	q2	q3	q4	act
1	0	0	0	A
0	1	0	1	A
1	1	0	0	B
0	1	1	0	B

**After reduction:**

q1	q2	q4	act
1	1		B
1			A
		1	A
			B

**Natural strategy:**

1.  $q1 \wedge q2 \rightarrow B$
2.  $q1 \vee q4 \rightarrow A$
3.  $\top \rightarrow B$



# Experimental evaluation

# Simple Voting with 2 candidates

$$\phi_1 \equiv \langle\langle c \rangle\rangle \Box ((finish_k \wedge vote_{i,j}) \rightarrow pun_i)$$

$$\phi_2 \equiv \langle\langle v_i \rangle\rangle \Box (\neg K_c vote_{i,j})$$

$$\phi_3 \equiv \langle\langle v_i \rangle\rangle \Box (finish_i \rightarrow vote_{i,j} \wedge \neg K_c vote_{i,j})$$

#V	Model generation	$\phi_1$				$\phi_2$				$\phi_3$			
		General synthesis	Natural synthesis	Compl. raw	Compl. optimized	General synthesis	Natural synthesis	Compl. raw	Compl. optimized	General synthesis	Natural synthesis	Compl. raw	Compl. optimized
1	0.03	<0.01	<0.01	156	26	<0.01	<0.01	9	3	<0.01	<0.01	9	3
2	0.05	<0.01	<0.01	991	131	<0.01	<0.01	9	3	<0.01	<0.01	9	3
3	0.21	0.15	0.15	4516	512	0.01	0.04	9	3	0.02	0.03	9	3
4	5.89	5.25	5.48	18043	1831	0.02	0.02	9	3	0.04	0.05	9	3
5	254.98	memout				25.02	10.15	9	3	28.56	12.68	9	3
6	timeout	-	-	-	-	-	-	-	-	-	-	-	-

## Natural strategy for $\phi_3$ found by STV

1.  $\neg vote_{1,2} \rightarrow vote_2$

***cost = 2***

2.  $\top \rightarrow idle$

***cost = 1***

Complexity:  **$2 + 1 = 3$**

# vVote with 2 candidates

$$\phi_4 \equiv \langle\langle v_1 \rangle\rangle \Diamond (checkWBB\_ok \vee checkWBB\_notok)$$

$$\phi_5 \equiv \langle\langle v_1, c \rangle\rangle \Diamond (vote_{1,1} \wedge K_c vote_{1,1}).$$

#V	gen.	$\phi_4$				$\phi_5$			
		Strat.	Strat. nat.	Cmp. std.	Cmp. red.	Strat.	Strat. nat.	Cmp. std.	Cmp. red.
1	0.04	<0.01	0.06	797	39	<0.01	0.02	863	42
2	0.24	<0.01	0.26	2170	124	<0.01	0.04	851	38
3	9.02	0.43	0.54	2105	122	0.22	0.41	851	38
4	526.16	29.55	21.83	2170	124	18.64	18.81	851	38
5	timeout	-	-	-	-	-	-	-	-

# Conclusions

- It's not enough that a voter has a strategy – **complexity** is important
- Natural Strategy complexity helps to estimate the mental difficulty
- Other important factors exists: time, money, etc.
- The presented methodology can be applied outside the e-voting domain
- STV can be used to find natural strategy, if one exists



Thank You